

# Implicit Regularization

A Statistical View

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# Machine learning

$$\text{test error} \leq \text{training error} + \sqrt{\frac{\text{complexity}}{n}}$$

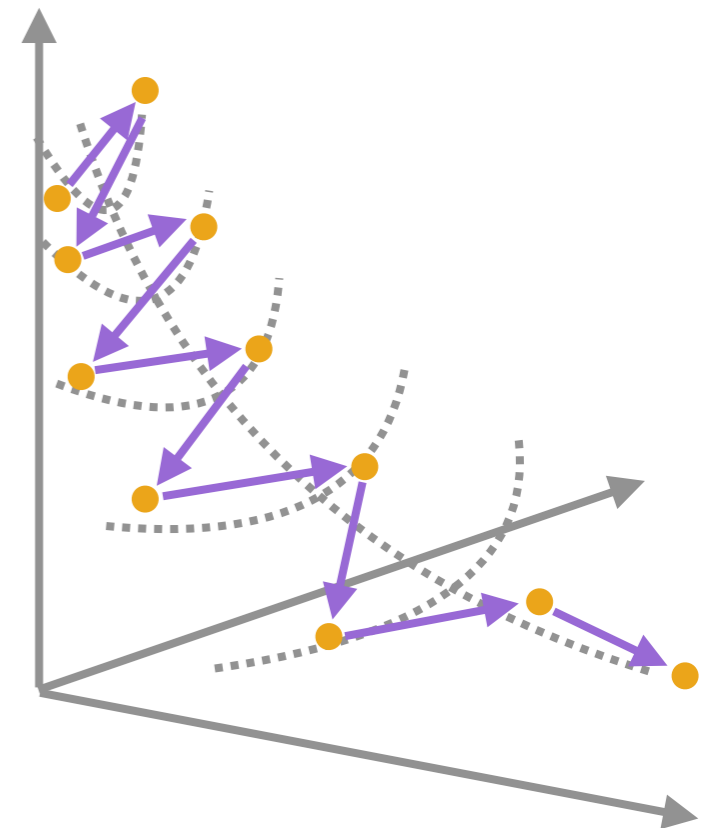
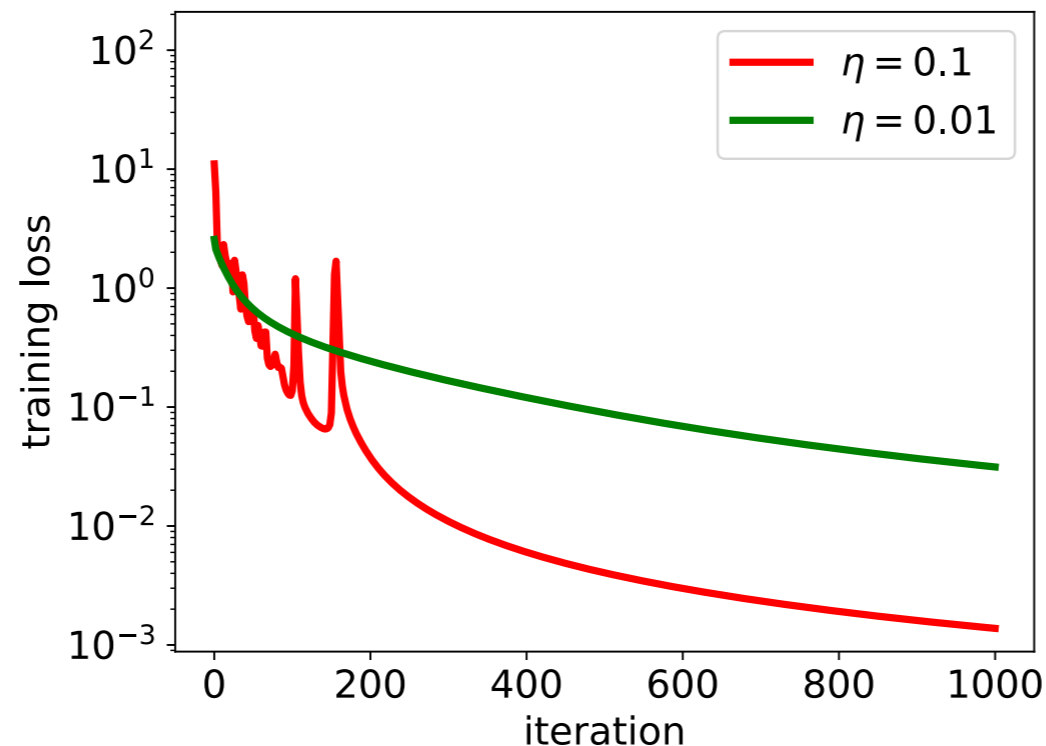
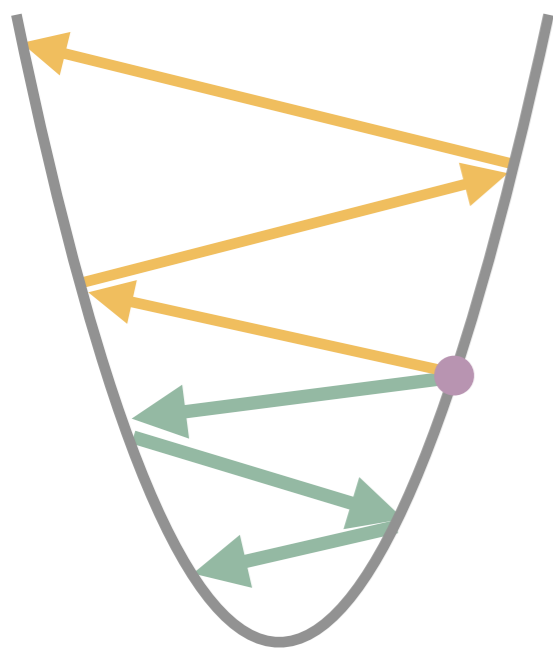
- optimization  $\leq$  gradient methods
- generalization  $\leq$  complexity control

# Machine learning

$$\text{test error} \leq \text{training error} + \sqrt{\frac{\text{complexity}}{n}}$$

- optimization  $\Leftarrow$  gradient methods

past work: large stepsize accelerates GD for logistic regression



# Machine learning

$$\text{test error} \leq \text{training error} + \sqrt{\frac{\text{complexity}}{n}}$$

- optimization  $\leq$  gradient methods
- generalization  $\leq$  complexity control

this talk: generalization, done together with optimization

# Complexity control

classical answer: **explicit control**

- model family
- norm regularization
- ...

deep learning: **implicit control via opt algo**

- early stopping
- stochastic averaging
- ...

*how good is implicit regularization?*

Bartlett. "For valid generalization the size of the weights is more important than the size of the network." NeurIPS 1996

# One of our results

For all Gaussian linear regression problems:

early stopping is

- always no worse
- sometimes much better

than  $\ell_2$ -regularization.

# Our approach

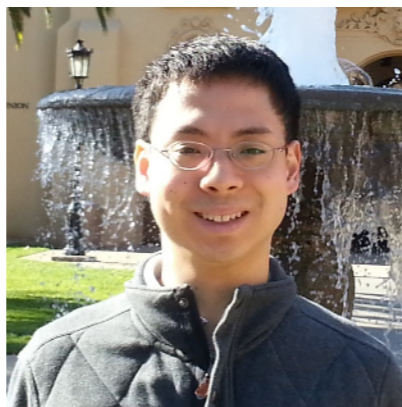
Instance-wise risk comparison ← instead of minimax

← high dimension

- GD vs ridge regression
- GD vs (online) SGD



Peter Bartlett



Jason Lee



Sham Kakade



Bin Yu

**Wu, Bartlett\*, Lee\*, Kakade\*, Yu\***. "Risk comparisons in linear regression: implicit regularization dominates explicit regularization." arXiv 2025

# Linear regression

finite signal-to-noise ratio



$$x \sim \mathcal{N}(0, \Sigma), \quad y = x^\top w^* + \mathcal{N}(0, 1) \quad \text{for } \|w^*\|_\Sigma \lesssim 1$$

problem determined by  $(\Sigma, w^*)$

excess risk / prediction error

$$\begin{aligned} R(w) &= \mathbb{E}(y - x^\top w)^2 - \mathbb{E}(y - x^\top w^*)^2 \\ &= \|w - w^*\|_\Sigma^2 \end{aligned}$$

$n$  iid samples  $(x_1, y_1), \dots, (x_n, y_n)$

$$X = \begin{bmatrix} x_1^\top \\ \vdots \\ x_n^\top \end{bmatrix} \quad Y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix}$$

# Explicit / implicit regularization

## ridge regression

hyperparameter:  $\lambda \geq 0$

$$\begin{aligned} w_{\lambda}^{\text{ridge}} &= \arg \min \frac{1}{n} \sum_{i=1}^n \|x_i^{\top} w - y_i\|^2 + \lambda \|w\|^2 \\ &= (X^{\top} X + n\lambda I)^{-1} X^{\top} Y \end{aligned}$$

## gradient descent

hyperparameter:  $t \geq 0$

- $w_0 = 0$
- for  $s = 1, \dots, t$ ,

$$w_s = w_{s-1} - \frac{\eta}{n} X^{\top} (X w_{s-1} - Y)$$

- $w_t^{\text{gd}} = w_t$

# Notation

- SVD

$$\Sigma = \sum_{i \geq 1} \lambda_i u_i u_i^\top \quad \lambda_1 \geq \lambda_2 \geq \dots$$

- head and tail divided by  $k$

$$\Sigma_{0:k} = \sum_{i \leq k} \lambda_i u_i u_i^\top \quad \Sigma_{k:\infty} = \sum_{i > k} \lambda_i u_i u_i^\top$$


- matrix  $M$ , vector  $v$

$$M^{-1} = \text{pseudoinverse of } M \quad \|v\|_M^2 = v^\top M v$$

# Bounds for ridge

\*possible to pin down constants via RMT

**Theorem.** For all  $\lambda \geq 0$ , in expectation


$$\mathbb{E}R(w_{\lambda}^{\text{ridge}}) \gtrsim \tilde{\lambda}^2 \|w^*\|_{\Sigma_{0:k^*}^{-1}}^2 + \|w^*\|_{\Sigma_{k^*:\infty}}^2 + \min \left\{ \frac{D}{n}, 1 \right\}$$

“ $\mathbb{E}$ ” can be made “w.h.p.”

same upper bound holds w.h.p.

*critical index*

$$k^* = \min \left\{ k : \lambda + \frac{\sum_{i>k} \lambda_i}{n} \geq c\lambda_{k+1} \right\}$$

*effective regularization*

$$\tilde{\lambda} = \lambda + \frac{\sum_{i>k^*} \lambda_i}{n}$$

*effective dimension*

$$D = k^* + \frac{1}{\tilde{\lambda}^2} \sum_{i>k^*} \lambda_i^2$$

# A ridge-type bound for GD

**Theorem** [WBLKY'25]. For all  $0 < \eta \lesssim 1/\text{tr}(\Sigma)$  and  $t \geq 0$ , w.h.p.

$$R(w_t^{\text{gd}}) \lesssim \tilde{\lambda}^2 \|w^*\|_{\Sigma_{0:k^*}^{-1}}^2 + \|w^*\|_{\Sigma_{k^*:\infty}}^2 + \frac{D}{n}$$

was  $\min \left\{ \frac{D}{n}, 1 \right\}$

*critical index*

$$k^* = \min \left\{ k : \frac{1}{\eta t} + \frac{\sum_{i>k} \lambda_i}{n} \geq c \lambda_{k+1} \right\}$$

*effective regularization*

$$\tilde{\lambda} = \frac{1}{\eta t} + \frac{\sum_{i>k^*} \lambda_i}{n}$$

was  $\lambda$

*effective dimension*

$$D = k^* + \frac{1}{\tilde{\lambda}^2} \sum_{i>k^*} \lambda_i^2$$

**GD is no worse than ridge.**

Proof. If  $D > n$ , set  $t = 0$ ; otherwise, set  $t = 1/(\eta \lambda)$ .

# GD dominates ridge

$$x \sim N(0, \Sigma), \quad y = x^\top w^* + N(0, 1) \quad \text{for } \|w^*\|_\Sigma \lesssim 1$$

**Theorem [WBLKY'25].** For **every** Gaussian linear regression,  $n \geq 1$ , and  $\lambda \geq 0$ , there is  $t$  such that: w.h.p.

$$R(w_t^{\text{gd}}) \lesssim \mathbb{E}R(w_\lambda^{\text{ridge}})$$

**Prior work.** Assume an isotropic prior,  $\mathbb{E}w^{*\otimes 2} \propto I$

$$\inf_\lambda \mathbb{E}R(w_\lambda^{\text{ridge}}) \leq \mathbb{E}R(w_t^{\text{gd}}) \leq 1.69 \mathbb{E}R(w_\lambda^{\text{ridge}})$$

next: GD can be much better than ridge

Ali, Kolter, Tibshirani. “A continuous-time view of early stopping for least squares regression.” AISTATS 2019

# Power law class

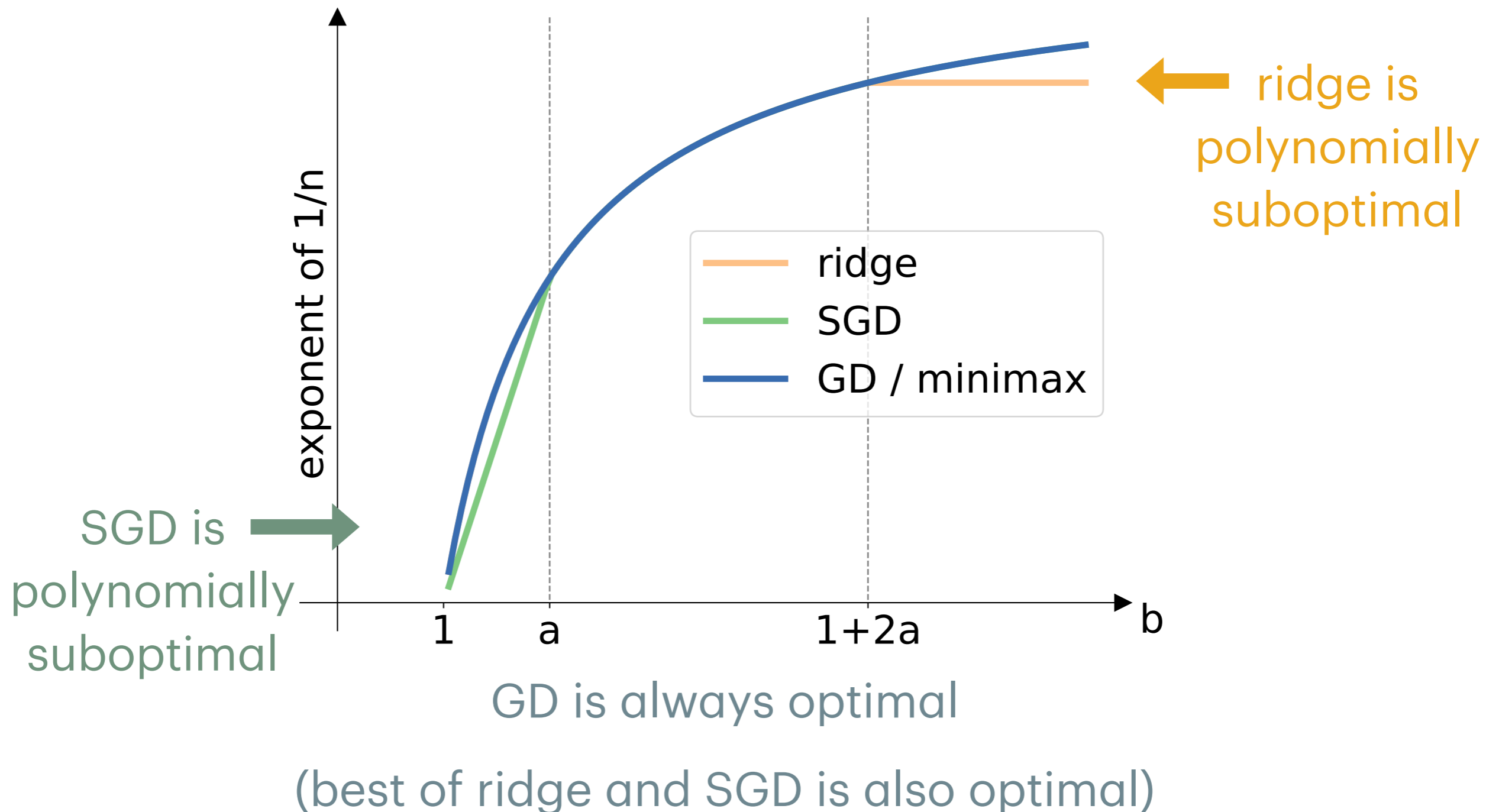
$$\lambda_i \approx i^{-a} \quad \lambda_i (u_i^\top w^*)^2 \approx i^{-b} \quad \text{for } a, b > 1$$

	$1 < b < a$	$a < b < 1 + 2a$	$b > 1 + 2a$
ridge	$O\left(n^{-\frac{b-1}{b}}\right)$		$\Omega\left(n^{-\frac{2a}{1+2a}}\right)$
SGD	$\tilde{\Omega}\left(n^{-\frac{b-1}{a}}\right)$	$\tilde{O}\left(n^{-\frac{b-1}{b}}\right)$	
GD	$O\left(n^{-\frac{b-1}{b}}\right)$		
minimax	$\Omega\left(n^{-\frac{b-1}{b}}\right)$		

GD is always optimal  
 ridge/SGD is only partially optimal

# Power law class

$$\lambda_i \approx i^{-a} \quad \lambda_i (u_i^\top w^*)^2 \approx i^{-b} \quad \text{for } a, b > 1$$



# Results so far

GD dominates ridge

- always no worse
- sometimes much better

**remark** (computation)

multi-pass SGD (sample with replacement)

- multi-pass SGD is no better than GD
- with correct stepsizes, multi-pass SGD  $\approx$  GD

# Why not known earlier?

fixed design is easy [DFKU'13, 6 pages]

but random design is hard

- instance-wise, not worst-case
- high-dim is surprising [BLLT'20, 44 pages]
- right tools 2019+

more surprise: GD vs (online) SGD

Dhillon, Foster, Kakade, Unga. “A risk comparison of ordinary least squares vs ridge regression.” JMLR 2013

Bartlett, Long, Lugosi, Tsigler. “Benign overfitting in linear regression.” PNAS 2020

# Batch / online

## gradient descent

- $w_0 = 0$
- for  $s = 1, \dots, t$ ,
$$w_s = w_{s-1} - \frac{\eta}{n} X^\top (X w_{s-1} - Y)$$
- $w_t^{\text{gd}} = w_t$

hyperparameter:  $t \geq 0$

## stochastic gradient descent

- $w_0 = 0, \eta_0 = \eta, N = n/\log n$
- for  $i = 1, \dots, n$ ,
$$\eta_i = \begin{cases} 0.1\eta_{i-1} & \text{if } i \% N = 0 \\ \eta_{i-1} & \text{else} \end{cases}$$
$$w_i = w_{i-1} - \eta_i (x_i^\top w_{i-1} - y_i) x_i$$
- $w_\eta^{\text{sgd}} = w_n$

hyperparameter:  $0 < \eta \lesssim 1/\text{tr}(\Sigma)$

compare implicit regularization: batch vs online

# Bounds for SGD

**Theorem.** For all  $0 < \eta \lesssim 1/\text{tr}(\Sigma)$ , in expectation

$$\mathbb{E}R(w_{\eta}^{\text{sgd}}) \approx \left\| \prod_{i=1}^n (I - \eta_i \Sigma) w^* \right\|_{\Sigma}^2 + \frac{D}{N}$$

matching upper / lower bounds

*effective steps*

$$N = n / \log n$$

“ $N$ ” can be made “ $n$ ”

*critical index*

$$k^* := \min \left\{ \frac{1}{\eta N} \geq c \lambda_{k+1} \right\}$$

*effective dimension*

$$D = k^* + \eta^2 N^2 \sum_{i > k^*} \lambda_i^2$$

effective  
regularization

Zou\*, Wu\*, Braverman, Gu, Kakade. “Benign overfitting of constant-stepsize SGD for linear regression.” COLT 2021

Wu\*, Zou\*, Braverman, Gu, Kakade. “Last iterate risk bounds of SGD with decaying stepsize for overparameterized linear regression.” ICML 2022

# SGD vs ridge

$$\text{excess risk} = \text{bias} + D/N$$

	SGD	ridge
<i>bias</i>	$\ e^{-\Theta(\eta N)\Sigma_{0:k^*}} w^*\ _{\Sigma_{0:k^*}}^2 + \ w^*\ _{\Sigma_{k^*:\infty}}^2$ bias decays faster	$\tilde{\lambda}^2 \ w^*\ _{\Sigma_{0:k^*}^{-1}}^2 + \ w^*\ _{\Sigma_{k^*:\infty}}^2$
<i>effective steps</i>	$N = n/\log n$	$N = n$
<i>critical index</i>	$\lambda_{k^*} \gtrsim \frac{1}{\eta N} \gtrsim \lambda_{k^*+1}$	$\lambda_{k^*} \gtrsim \lambda + \frac{\sum_{i>k^*} \lambda_i}{n} \gtrsim \lambda_{k^*+1}$
<i>effective regularization</i>	$\tilde{\lambda} = \frac{1}{\eta N}$ constraint	$\tilde{\lambda} = \lambda + \frac{\sum_{i>k^*} \lambda_i}{n}$ constraint
<i>effective dimension</i>	$\eta \lesssim 1/\text{tr}(\Sigma)$ $D = k^* + \frac{1}{\tilde{\lambda}^2} \sum_{i>k^*} \lambda_i^2$	heavy tail

GD dominates ridge; would GD dominate SGD?

# GD does not dominate SGD

**Theorem** [WBLKY'25].  $n \geq 1$ . For a sequence of  $d$ -dim problems

$$d \geq n^2 \quad w^* = \begin{bmatrix} n^{0.45} \\ 0 \\ \vdots \\ 0 \end{bmatrix} \quad \Sigma = \begin{bmatrix} n^{-0.9} & & & \\ & 1/d & & \\ & & \ddots & \\ & & & 1/d \end{bmatrix}$$

we have  $\|w^*\|_{\Sigma}^2 \leq 1$ , moreover

- for all  $0 < \eta \lesssim 1$  and  $t \geq 0$ ,  $\mathbb{E}R(w_t^{\text{gd}}) = \Omega(n^{-0.2})$
- for  $\eta \approx 1$ ,  $\mathbb{E}R(w_{\eta}^{\text{sgd}}) = O(\log(n)/n)$

in high-dim  
online learning can be poly better than batch!

# A lower bound for GD

**Theorem** [WBLKY'25]. For all  $0 < \eta \lesssim 1/\text{tr}(\Sigma)$  and  $t \geq 0$

$$\mathbb{E}R(w_t^{\text{gd}}) \gtrsim \left( \frac{\sum_{i>\ell^*} \lambda_i}{n} \right)^2 \|w^*\|_{\Sigma_{0:\ell^*}^{-1}}^2 + \|w^*\|_{\Sigma_{\ell^*:\infty}}^2 + \min \left\{ \frac{D}{n}, 1 \right\}$$

*effective dimension*  $D = k^* + \frac{1}{\tilde{\lambda}^2} \sum_{i>k^*} \lambda_i^2$  as before...

*benign overfitting index*  $\ell^* = \min \left\{ k : \frac{\sum_{i>k} \lambda_i}{n} \geq c\lambda_{k+1} \right\}$

GD variance = ridge variance

GD bias  $\geq$  OLS bias

in high-dim

OLS bias can be large

*when would GD dominate SGD?*

# A SGD-type bound for GD

**Theorem** [WBLKY'25]. For all  $0 < \eta \lesssim 1/\text{tr}(\Sigma)$  and  $0 \leq t \lesssim n$ , w.h.p.

$$R(w_t^{\text{gd}}) \lesssim \left\| (I - \eta \Sigma)^{t/2} w^* \right\|_{\Sigma}^2 + \frac{D}{n} + \left( \frac{D_1}{n} \right)^2$$

*critical index*

$$k^* := \min \left\{ \frac{1}{\eta t} \geq c \lambda_{k+1} \right\} \quad \leftarrow \text{same as SGD}$$

*effective dimension*

$$D = k^* + \eta^2 t^2 \sum_{i > k^*} \lambda_i^2 \quad \leftarrow \text{when } t = \Theta(N)$$

*order-1 effective dim*

$$D_1 = k^* + \eta t \sum_{i > k^*} \lambda_i$$

- $D \leq D_1$ , always
- in the hard example,  $D \ll D_1$

*when would  $D_1 \lesssim D$ ?*

# Spectrum condition

**Assumption.** Spectrum decays *fast and continuously*

$$\text{for all } \tau > 1, \quad \tau \sum_{\lambda_i < 1/\tau} \lambda_i \lesssim \#\{\lambda_i \geq 1/\tau\}$$

satisfied by

- $\lambda_i \approx a^{-i}$  for  $a > 1$
- $\lambda_i \approx i^{-a}$  for  $a > 1$
- rules out benign overfitting
- implies  $D_1 \lesssim k^* \leq D$

violated by

- $\lambda_i \approx i^{-1} \log^{-a}(i)$  for  $a > 1$
- $(\lambda_i)_{i \geq 1}$  in the hard example

$$(n^{-0.9}, 1/d, \dots, 1/d) \text{ for } d \geq n^2$$

# GD dominates SGD in a subclass

**Assumption.** Spectrum decays fast and continuously

$$\text{for all } \tau > 1, \quad \tau \sum_{\lambda_i < 1/\tau} \lambda_i \lesssim \#\{\lambda_i \geq 1/\tau\}$$

$$x \sim \mathcal{N}(0, \Sigma), \quad y = x^\top w^* + \mathcal{N}(0, 1) \text{ for } \|w^*\|_\Sigma \lesssim 1$$

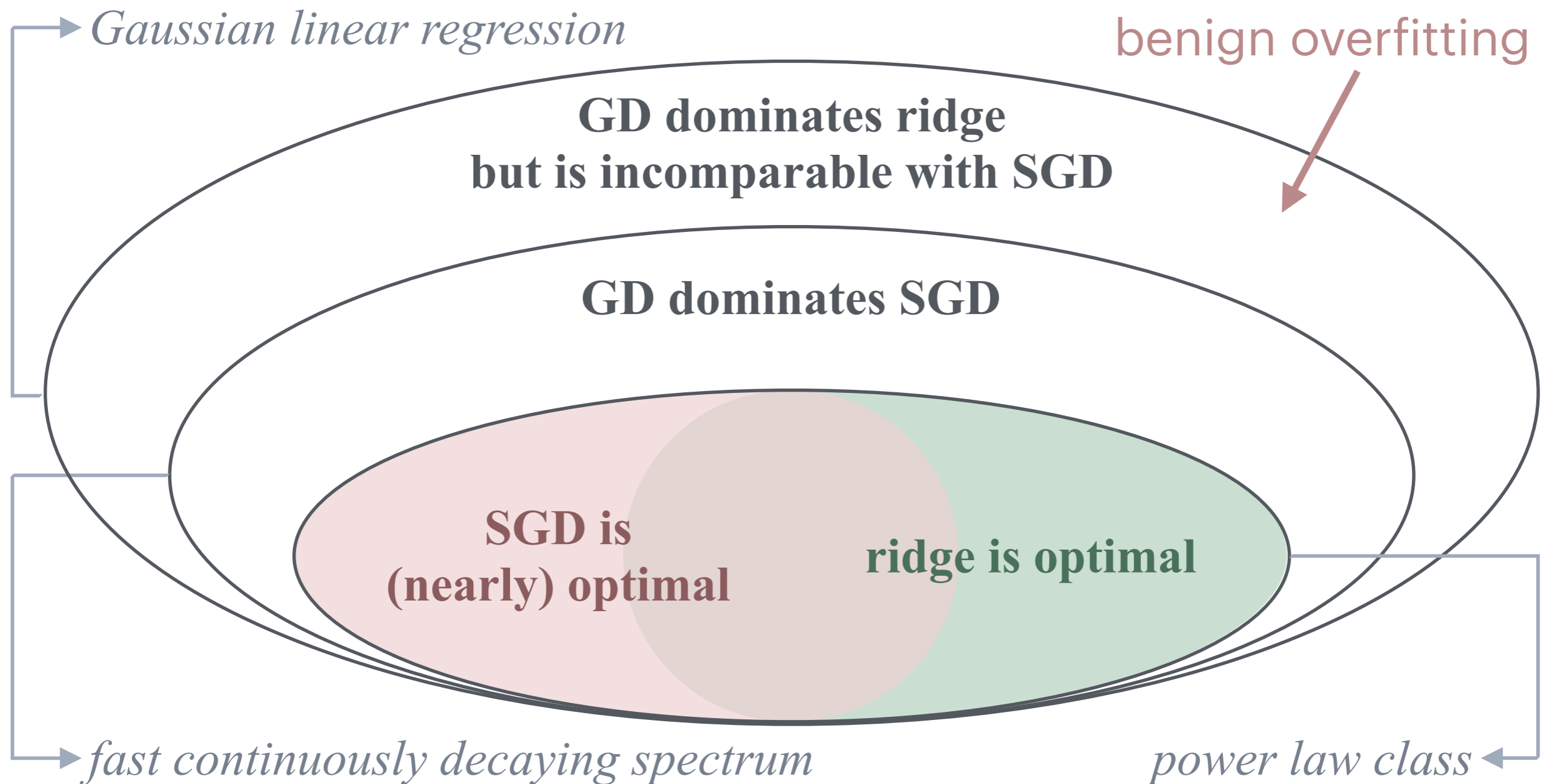
**Theorem [WBLKY'25].** For every Gaussian linear regression satisfying the above,  $n \geq 1$ , and  $0 \leq \eta \lesssim 1$ , there is  $t$  such that

$$\mathbb{E}R(w_t^{\text{gd}}) \lesssim \mathbb{E}R(w_\eta^{\text{sgd}})$$

**Proof.** Assumption implies  $D_1 \lesssim k^* \leq D$ .

no constraint on  $w^*$

# Contributions



“dominance”: always no worse, sometimes much better

# How to reuse data?

- GD and SGD are incomparable
- multi-pass SGD is no better than GD
- but multi-epoch SGD (sample without replacement) dominates both
  - first epoch recovers SGD
  - continuous limit  $\eta \rightarrow 0$  recovers GF

data reuse strategy makes poly differences  
call for a new theory!